

Linearity of Determinants

given row vectors $\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_n$ each has n components

then $T(\vec{x}) = \det \begin{bmatrix} \vec{v}_1 \\ \vdots \\ \vec{v}_{i-1} \\ \vec{x} \\ \vec{v}_{i+1} \\ \vdots \\ \vec{v}_n \end{bmatrix} : \mathbb{R}^{1 \times n} \rightarrow \mathbb{R}$ is a LT

next, use properties: $T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$
 $T(k\vec{x}) = k T(\vec{x})$

likewise, $\det \begin{bmatrix} \vec{v}_1 \\ \vdots \\ \vec{x} + \vec{y} \\ \vdots \\ \vec{v}_n \end{bmatrix} = \det \begin{bmatrix} \vec{v}_1 \\ \vdots \\ \vec{x} \\ \vdots \\ \vec{v}_n \end{bmatrix} + \det \begin{bmatrix} \vec{v}_1 \\ \vdots \\ \vec{y} \\ \vdots \\ \vec{v}_n \end{bmatrix}$ no parens

and $\det \begin{bmatrix} \vec{v}_1 \\ \vdots \\ k\vec{x} \\ \vdots \\ \vec{v}_n \end{bmatrix} = k \det \begin{bmatrix} \vec{v}_1 \\ \vdots \\ \vec{x} \\ \vdots \\ \vec{v}_n \end{bmatrix}$

given $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \mathbb{R}^{2 \times 2}$ know $\det A = ad - bc$

$\therefore$ given $B = \begin{bmatrix} a/k & b/k \\ c & d \end{bmatrix}$ then $\det B = \frac{a}{k}d - \frac{b}{k}c$
 $= \frac{1}{k}(ad - bc) = \frac{1}{k} \det A$

also, $B = A \rightarrow \mathbb{I} \cdot \frac{1}{k}$

$= \begin{bmatrix} a & b \\ c & d \\ \frac{1}{k} & \frac{1}{k} \end{bmatrix}$ then $\det B = \frac{1}{k} \det A$

swap rows:

✓ 1 inversion of A

$L^k \quad K \quad J$

swap rows:

if $B = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$ then $\det B = (-1)^1 \det A$ ← 1 inversion of A

$k(c+d) = kc + kd$ add I of A:

$$\text{then } B = \begin{bmatrix} a+kc & b+kd \\ c & d \end{bmatrix} \quad \text{then } \det B = (a+kc)d - c(b+kd) \\ = \cancel{ad} + \cancel{kcd} - \cancel{bc} - \cancel{kcd} \\ = \det A$$

generalize:

- if B is obtained by dividing a row of A by a scalar k then $\det B = \frac{1}{k} \det A$
- if B is obtained from A by a row swap then $\det B = -\det A$ ← "determinant is alternating on rows"
- if B is obtained from A by adding a multiple of A to another row then $\det B = \det A$

furthermore, if A, B are $n \times n$ matrices and $m \in \mathbb{Z}^+$ then:

- $\det(AB) = \det A \det B$
- $\det(A^m) = (\det A)^m$

also $A \sim B \rightarrow \det A = \det B$

also if A is invertible (or $\det A \neq 0$) then $\det(A^{-1}) = \frac{1}{\det A} = (\det A)^{-1}$

proof:

given A is invertible $\Rightarrow I_n = AA^{-1}$

$$\det(I_n) = \det(AA^{-1})$$

$$\frac{1}{\det A} = \frac{\det A}{\det A} \det A^{-1}$$

$$\frac{1}{\det A} = \det A^{-1} \quad \square$$

↑
reciprocal

§6.3 Determinant Applications

recall: given linear system $\begin{cases} 2x_1 - x_2 = 3 \\ x_1 + 2x_2 = 1 \end{cases}$ can be written as $\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$

$$A \vec{x} = \vec{b}$$

$$\vec{x} = A^{-1} \vec{b}$$

$$\det A = 4 - (-1) = 5$$

$$= \frac{1}{\det A} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$= \frac{1}{5} \begin{bmatrix} 7 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 7/5 \\ -1/5 \end{bmatrix}$$

Generalize:

$$\text{given } A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}, \vec{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$\text{then } A^{-1} = \frac{1}{\det A} \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}$$

$$A^{-1} \vec{b} = \frac{1}{\det A} \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$\text{row 1 } a_{22}b_1 - a_{12}b_2 = \det \begin{bmatrix} b_1 & a_{12} \\ b_2 & a_{22} \end{bmatrix} \quad \text{row 2 } -a_{21}b_1 + a_{11}b_2 = \det \begin{bmatrix} a_{11} & b_1 \\ a_{21} & b_2 \end{bmatrix}$$

$A_{\vec{b},1}$

$A_{\vec{b},2}$

Cramer's Rule: solution of system $A\vec{x} = \vec{b}$ is:
(assume A is 2×2 invertible matrix)

$$x_1 = \frac{\det [A_{\vec{b},1}]}{\det A}, \quad x_2 = \frac{\det [A_{\vec{b},2}]}{\det A}$$

$$\text{revisit: solve } \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$A \vec{x} = \vec{b}$$

$$\det A = 5$$

$$A_{\vec{b},1} = \begin{bmatrix} 3 & -1 \\ 1 & 2 \end{bmatrix} \quad \det A_{\vec{b},1} = 6 + 1 = 7$$

$$x_1 = \frac{\det A_{\vec{b},1}}{\det A} = \frac{7}{5}$$

$$A_{\vec{b},2} = \begin{bmatrix} 2 & 3 \\ 1 & 1 \end{bmatrix} \quad \det A_{\vec{b},2} = 2 - 3 = -1$$

$$\vec{x} = \begin{bmatrix} 7/5 \\ -1/5 \end{bmatrix}$$

$$A_{\vec{b},2} = \begin{bmatrix} 2 & 3 \\ 1 & 1 \end{bmatrix} \quad \det A_{\vec{b},2} = 2-3 = -1 \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \vec{x} = \begin{bmatrix} 1 \\ -1/5 \end{bmatrix}$$

$$x_2 = \frac{\det A_{\vec{b},2}}{\det A} = -\frac{1}{5}$$

ex solve the system

$$\begin{cases} x - y + 2z = -3 \\ 3x + z = -2 \\ -x + 2y = -2 \end{cases}$$

write as $A\vec{x} = \vec{b}$:

$$\begin{bmatrix} 1 & -1 & 2 \\ 3 & 0 & 1 \\ -1 & 2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -3 \\ -2 \\ -2 \end{bmatrix}$$

$$\det A = \det \begin{bmatrix} 1 & -1 & 2 \\ 3 & 0 & 1 \\ -1 & 2 & 0 \end{bmatrix} = 1 \det \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix} - (-1) \det \begin{bmatrix} 3 & 1 \\ -1 & 0 \end{bmatrix} + 2 \det \begin{bmatrix} 3 & 0 \\ -1 & 2 \end{bmatrix}$$

$$= -2 + 1 + 2(6) = 11 = \det A$$

$$\det(A_{\vec{b},1}) = \det \begin{bmatrix} -3 & -1 & 2 \\ -2 & 0 & 1 \\ -2 & 2 & 0 \end{bmatrix} = 0 \quad x = \frac{0}{11} = 0$$

$$\det(A_{\vec{b},2}) = \det \begin{bmatrix} 1 & 3 & 2 \\ 3 & -2 & 1 \\ -1 & 2 & 0 \end{bmatrix} = -11 \quad y = \frac{-11}{11} = -1 \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ -2 \end{bmatrix}$$

$$\det(A_{\vec{b},3}) = \det \begin{bmatrix} 1 & -1 & -3 \\ 3 & 0 & -2 \\ -1 & 2 & -2 \end{bmatrix} = -22 \quad z = \frac{-22}{11} = -2$$

Cramer's Rule - with $n \times n$ invertible matrix A

given $A\vec{x} = \vec{b}$

Components of solution vector $\vec{x}$ are: $x_i = \frac{\det(A_{\vec{b},i})}{\det A}$

where $A_{\vec{b},i}$ is obtained by replacing the i th column of A by $\vec{b}$

but what IS a determinant ???

recall: $n \times n$ matrix A is orthogonal iff $A^T A = I_n$
 or $A^{-1} = A^T$

also recall: given $n \times n$ matrices A, B

$$\begin{aligned} \rightarrow \det A^T &= \det A \\ \det (AB) &= \det A \det B \\ \det A^m &= (\det A)^m \quad m \in \mathbb{Z}^+ \end{aligned}$$

$$A^T A = I_n$$

$$\det(A^T A) = \det I_n$$

$$\det A^T \det A = 1$$

$$\det A \det A$$

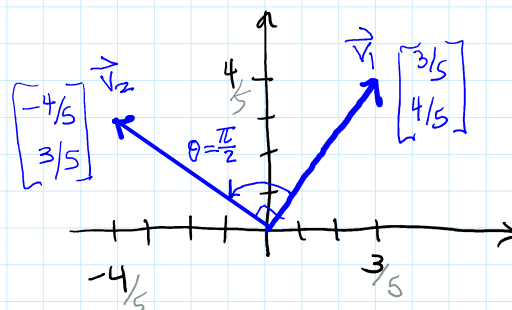
$$(\det A)^2 = 1 \Rightarrow \det A = \pm 1$$

thm: determinant of orthogonal matrix is either 1 or -1

ex. use CCW $\pi/2$ rotation matrix: $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

$$\det \begin{bmatrix} 3/5 & -4/5 \\ 4/5 & 3/5 \end{bmatrix} = \frac{9}{25} - \left(-\frac{16}{25} \right) = 1$$

$\vec{v}_1$ $\vec{v}_2$



def'n: orthogonal $n \times n$ matrix A with $\det A = 1$ is a rotation matrix